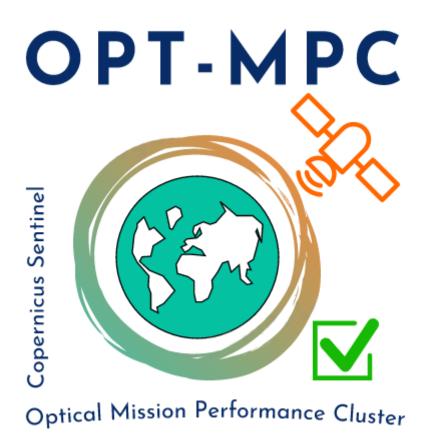
COPERNICUS SPACE COMPONENT SENTINEL OPTICAL IMAGING MISSION PERFORMANCE CLUSTER SERVICE

Data Quality Report

Sentinel-2 L1C MSI

December 2023



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List of Changes

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1 Introduction

1.1 Scope of the document

This document provides the data quality status of Copernicus Sentinel-2 mission L1C products. Please note that the data quality status before the beginning of 2023 is covered by the <u>Annual Performance Report of 2022</u>. Please refer to this document as well as former Data Quality Reports (DQR) if needed.

The DQR documents:

- processing chain improvements associated to each Processing Baseline (Section 2),
- the calibration description and status (Section 3),
- the measured product performance vs. specifications (Section 4),
- observed anomalies and known issues (Section 7),
- general information on products (Section 8).

Note that a reference article provides an in-depth presentation of Sentinel-2 Calibration and Validation methods and results after one year in operation (F. Gascon *et al.*, "Copernicus Sentinel-2 Calibration and Products Validation Status", RSE, 2017).

Since May 2018, a Data Quality Report for Level 2A products is also available from the <u>Sentinel-2 Document</u> <u>Library</u>.

1.2 Main points for the Reporting Period

- New radiometric and geometric calibration for both Sentinel-2A and Sentinel-2B (see section 3),
- Assessment of the current geometric performances (see section 4.3),
- Imminent deployment of Copernicus DEM at 30m resolution for Sentinel-2 products (more details here),
- Availability of the Copernicus Sentinel-2 Collection-1 data (see section 8.1),
- New organization of the Sentinel Online website: please visit the SentiWiki webpages,
- Phase out of the Copernicus Data Hub Services (more details <u>here</u>). From now on please refer to the Copernicus Data Space Ecosystem to download Sentinel-2 products.

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2 Processing Baseline Status

On December 6th, 2022, the **processing baseline 05.09** was deployed. The format of the L1C and L2A products within this new PB remains the same as outlined in the current Product Specification Document (version 14.9).

The operational processor deployed for this processing baseline (version 6.1) is the same used to generate the Copernicus Sentinel-2 Collection-1 (for more details please refer to the section 8.1). The particularity of the current processor is that it can operate with both the Copernicus DEM at 90 meters ground spatial resolution, and/or with its finer defined version at 30 meters resolution. Currently, the 90 m version of the DEM will continue being used for the nominal productions while the 30 m version of the DEM is being used for the historical archive reprocessing.

The Processing Baseline identifier 05.09 tags the operational products generated with the 90 m version of the Copernicus DEM. The Processing Baseline identifier 05.00 tags the Copernicus Sentinel-2 Collection-1 products.

The following evolutions are included:

Update of the radiometric saturation threshold to allow saturation mask computation. This is the final fix for anomaly #13 and ensures that the saturation mask (QUALIT mask layer 8) is now fully operational. Users are advised that radiometric accuracy requirements are not applicable to saturated pixels.

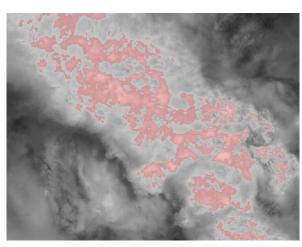


Figure 1. B08 image with saturation mask overlayed (semi-transparent red).

Partially corrected mask: flag pixels where there is a crosstalk between one band and another one which is saturated. With processing baseline 05.XX, the partially corrected quality mask (QUALIT mask layer 7) becomes operational. The radiometric accuracy of partially corrected pixels may be slightly degraded.

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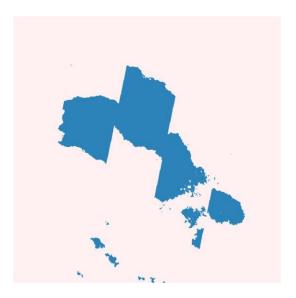


Figure 2. Partially corrected pixel mask for B12.

The mask correctly reflects the impact of crosstalk from B10.

In addition to the evolutions included in the processing baseline 05.09, we remind here that a **radiometric offset** on reflectance digital numbers has been introduced with processing baseline 04.00 deployed on January 25th, 2022. Then, the dynamic range is shifted by a band-dependent constant: RADIO_ADD_OFFSET. This offset allows encoding negative surface reflectances that may occur over very dark surfaces. From the user's point of view, the L1C Top of Atmosphere (TOA) reflectance (L1C_TOA) shall be retrieved from the output radiometry as follows:

- Digital Number DN=0 remains the "NO_DATA" value
- For a given DN in [1; 1;2^15-1], the L1C TOA reflectance value is:

L1C_TOAi = (L1C_DNi + RADIO_ADD_OFFSETi) / QUANTIFICATION_VALUEi

The radiometric offset value is reported in the field

General_Info/Product_Image_Characteristics/Radiometric_Offset_List/RADIO_ADD_OFFSET

of the User Product Metadata, as well as in the field

Image_Data_Info/Radiometric_Info/Radiometric_Offset_List/RADIO_ADD_OFFSET

of the Datastrip Metadata. It is set to -1000 Digital counts for all spectral bands.

For further information on the former processing baselines, please refer to https://omcs.atlassian.net/wiki/spaces/CSWK/pages/407406327/S2+Processing#Processing-Baseline.

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3 Calibration status

3.1 Instrument settings

There has been no change in the Sentinel-2A or Sentinel-2B instrument settings since the beginning of the year 2023.

3.2 Radiometric Calibration Status

3.2.1 Overview

Radiometric calibration is performed routinely at the beginning of each month. It includes a dark signal calibration as well as an absolute and relative gain calibration, and results in the update of the R2EQOG and R2ABCA calibration files used by the processor to generate Level-1C products:

- R2EQOG calibration file contains information to perform the equalisation on ground, in correcting the measured signal from the non-linearity of the pixel response and the non-uniformity behaviour of each pixel with the others. The objective is to get a uniform image when the observed landscape is uniform.
- R2ABCA calibration file contains the absolute calibration coefficient for each spectral band to convert the equalized signal into equivalent radiance at the entrance of the MSI sensor.

The table below provides the start validity dates of R2ABCA and R2EQOG calibration files (a couple of days after the monthly calibration itself) released since the beginning of 2023.

Table 3-1: Start validity date of R2ABCA and R2EQOG calibration files released in 2023

Month	S2A	S2B
January	12/01/2023	24/01/2023
February	09/02/2023	21/02/2023
March	09/03/2023	23/03/2023
April	18/04/2023	20/04/2023
May	16/05/2023	17/05/2023
June	15/06/2023	15/06/2023
July	12/07/2023	25/07/2023
August	09/08/2023	17/08/2023
September	19/09/2023	19/09/2023
October	18/10/2023	20/10/2023
November	09/11/2023	16/11/2023

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Decontamination operations are scheduled once a year.

3.2.2 Sentinel-2A

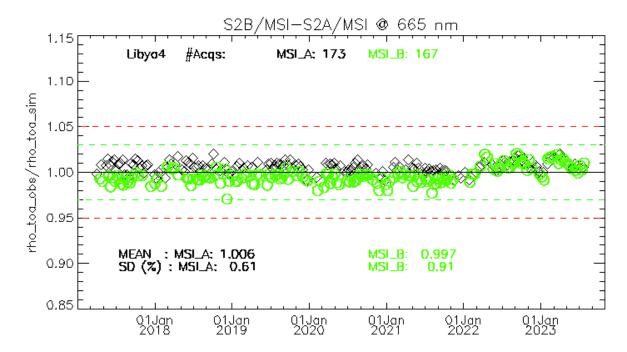
A decontamination of the instrument was performed on the $6^{th} - 7^{th}$ of November 2023. The calibration coefficients were updated on the 9^{th} of November.

3.2.3 Sentinel-2B

A decontamination was performed on $12^{th} - 13^{th}$ December 2022. The post-decontamination radiometric calibration was implemented on 19^{th} of December.

With the introduction of the baseline 04.00 on 25th January 2022, a radiometric harmonization between Sentinel-2A and Sentinel-2B (keeping Sentinel-2A as reference) was introduced. Indeed, among the evolution of this baseline the mitigation of the radiometric differences between both satellites was set by applying a radiometric bias correction of 1.1 % to Sentinel-2B VNIR bands B01 to B09.

The harmonization was effective from 09:00 UTC. The first Sentinel-2B sensing using the updated R2ABCA calibration file was: 20220125T073939. The time series below (Figure 3) shows this change in the radiometry for Sentinel-2B since the introduction of this radiometric correction factor (January 2022) and highlights the current alignment between Sentinel-2A and Sentinel-2B for Libya4 PICS Cal/Val site.



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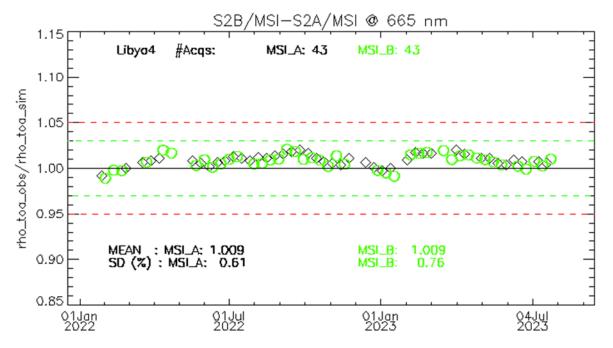


Figure 3: Time-series of the elementary ratios (observed/simulated) signal from MSI-A (black diamonds) and MSI-B (green dots) over the period (top) March 2017 up to August 2023 and (bottom) January 2022 - August 2023 for band B04 from Libya4 PICS Cal/Val site.

Dashed-green and orange lines indicate the 3% and 5% error respectively.

3.3 Geometric Calibration Status

3.3.1 Overview

Geometric calibration is performed to ensure the maintenance of the best geometry in the images by estimating the parameters of the Sentinel-2 MSI geometric model (orientation of the viewing frames and lines of sight of the detectors of the different focal planes). It results in updated SPAMOD calibration files, that contains the bias values for each angle (roll, pitch, yaw) in MSI geometric model viewing frame.

The table below provides the start validity dates of the last SPAMOD calibration file released for both S2A and S2B.

Table 3-2 : Start validity date of the SPAMOD calibration files used in operation

S2A	S2B
23/11/2023	04/05/2023
	23/11/2023

Since 30 March 2021 (PB 03.00), the geometric refinement for Sentinel-2 products was deployed over the Euro-Africa region and then in August worldwide (except Antarctica, some isolated islands and some high

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latitude areas), improving the multi-temporal co-registration and the relative geolocation accuracy of the products (see section 4.2 for more details).

The geometric refinement relies on the Sentinel-2 Global Reference Image (GRI). The GRI is a set of Level-1B images (in sensor frame) covering the whole globe with highly accurate geolocation information obtained through a spatio-triangulation algorithm using reference Ground Control Points. The images use the reference band (B04) and are mostly (but not entirely) cloud-free. In particular, the GRI is not meant to be a cloud-free mosaic of the globe. Thanks to the geometric refinement, all refined products inherit the same absolute geolocation performance.

With PB 03.00, a new Digital Elevation Model (DEM), the Copernicus DEM, is used to orthorectify the L1C products. This improves the local geolocation for all products in mountainous areas. This applies also to unrefined products, although the improvement is more effective for refined products.

3.3.2 Sentinel-2A

The latest geometric calibration was deployed on November 23rd, 2023 to improve the geolocation of unrefined products. The correction concerned mostly the roll and yaw angles.

3.3.3 Sentinel-2B

As for Sentinel-2A, the latest geometric calibration was deployed on November 23rd, 2023 to improve the geolocation of unrefined products. The correction concerned mostly the roll and yaw angles.

On May 4th, 2023 a geometric calibration has been deployed to improve the multispectral registration. Before that date, the latest multispectral registration results have highlighted that the SWIR/VNIR pairs are above mission specifications due to an offset of -0.2 pixels in the along-track component.

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4 Measured Product Performances

4.1 Performances Overview

The following overview table provides a summary of the Level-1C products data quality performances measured on products in Processing Baselines 02.01 and higher, for a set of key mission requirements.

Similar performances are observed for both S2A and S2B satellites.

Table 4-1: Summary of Sentinel-2 L1C products measured performances for mission key requirements.

Requirement	Description	Measured performance	
Absolute geolocation	The geo-location uncertainty shall be better than 20 m at 2σ confidence level (unrefined products)	< 15 m at 95.5% confidence (unrefined products)	
Multi-temporal registration	The spatial co-registration accuracy of Level 1c data acquired at different dates over the same geographical area shall be better than or equal to 0.3 SSD at 2 σ confidence level.	< 5 m at 95.5% confidence (refined products) for S2B and slightly above the specifications for S2A (6.2 m at 95.5% confidence)	
Multi-spectral registration	The inter-channel spatial co-registration of any two spectral bands shall be better than 0.30 of the coarser achieved spatial sampling distance of these two bands at 3σ confidence level.	slightly above the specifications for S2A (6.2	
Absolute radiometric uncertainty	The absolute radiometric uncertainty shall be better than 5 % (goal 3%). (see Table 4-3 in this document)	· ·	
SNR	The Signal-to-Noise Ratio (SNR) shall be higher than specified values (see Table 4-4 in this document)	All bands compliant with > 27% margin	

Measured performances are detailed in the following sections.

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4.2 Geometric Performance

4.2.1 Geometric Refinement and Global Reference Image (GRI)

Since March 2021 (processing Baseline 03.00) a geometric refinement step is used to improve the multi-temporal geolocation performance. Thanks to this processing, the performance of refined products is notably improved compared with the performance of the unrefined ones.

Validation results indicate the following performances for the refined products:

- Absolute geolocation: better than 6 m
- Multi-temporal co-registration (same or different satellites), same repeat orbit: better than 5 m at 95% confidence
- Multi-temporal co-registration, different repeat orbits: better than 5 m for S2B and slightly above for S2A.

4.2.2 Refinement coverage and fallback analysis

In order to avoid any case of badly refined products, refining is disabled if some quality criteria are not met ("fallback" case). Another instance of non-refined products is when there is no product in the GRI covering the current datastrip ("unrefined" case). This happens for instance over Antarctica.

Figure 4 provides the rate of unrefined products for S2A and S2B. The number of unrefined and fallback datastrips is equivalent for both S2A and S2B.

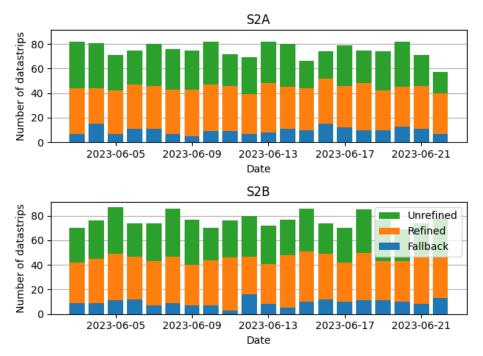


Figure 4: Number of refined (orange), unrefined (products without GRI, green) and fallback (blue) datastrips per day.

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The following maps provide the location of the datastrips in fallback based on different criteria and unrefined for a cycle period during February 2023. The cloud cover criteria is active mainly for high latitude products in the Northern hemisphere (winter season). The criteria on the number of valid zones also rejects some cloudy products as well as products with a large part over the Ocean. The criteria on the number of GCPs rejects a few products over very small, isolated islands. The criteria on the maximum distance at the corners of the datastrip and the one on the standard deviation of shifts mostly affect long datastrips on continents. Finally, unrefined datastrips (without a GRI product for refinement) are located at high latitudes and Antarctica, on very small islands or on open Ocean.

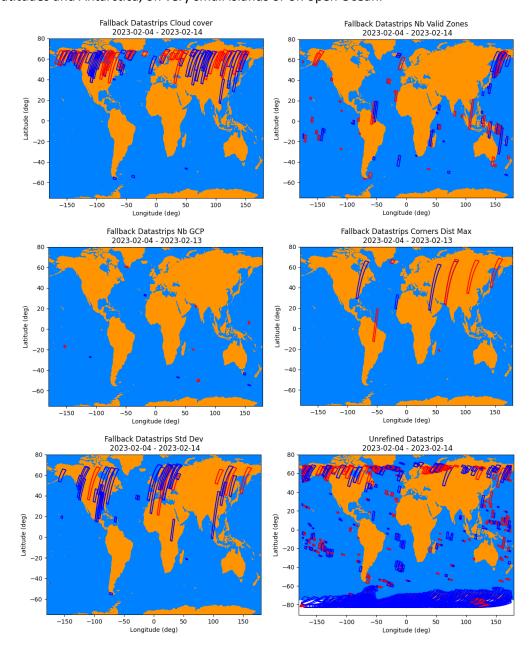


Figure 5 : Location of datastrips in fall-back and unrefined over a cycle period in February 2023 for S2A (red datastrips) and S2B (blue datastrips)

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4.2.3 Relative Geolocation

4.2.3.1 Unrefined products

Since the activation of the global refinement in August 2021, the performance is estimated on a limited set of unrefined products. Figure 6 shows the geolocation performance for the unrefined products relative to the Sentinel-2 GRI. Please note that the real absolute performance is expected to be a little worse due to the GRI absolute geolocation uncertainty (6 m).

On November 23, 2023, the geometric calibration has been updated (see section 3.3). Preliminary results presented on Figure 6 indicate that the geolocation performance of unrefined products has improved following this update. In particular, the across-track (ACT) bias has been reduced.

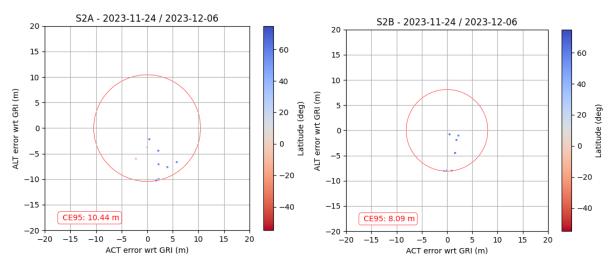


Figure 6: Relative geolocation performance for unrefined products. Left: S2A, Right: S2B.

4.2.3.2 Refined products

The geometric refinement performance is measured on a set of sample tiles around the globe. In May 2023, new tiles have been introduced over Southern America. This change of sampling explains the apparent evolution of the relative geolocation results but the actual performance has remained stable over the recent period for both satellites at comparable latitudes.

The performance of S2B is very satisfactory, showing biases below 1 m and a mean circular error at 95% confidence 4.6 m.

The performance of S2A is significantly worse with an along-track bias of 2 m and mean circular error of 7 m. This difference is due to outlier products at latitudes below 20° South. This issue is currently under investigation.

Please note that, as for the unrefined products, the real absolute performance is expected to be a little worse due to the GRI absolute geolocation uncertainty (6 m).

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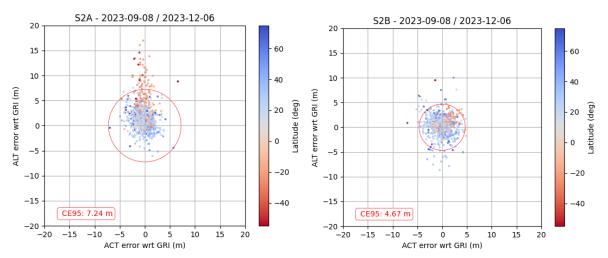


Figure 7: Relative geolocation performance for refined products. Left: S2A, Right: S2B

4.2.4 Absolute Geolocation

Absolute geolocation is assessed independently of the GRI. This absolute performance is computed on Level-1C products compared with reference images. The algorithm used for geometrical calibration with Level-1B products has been adapted to Level-1C products. Only the B4 spectral band is chosen for validation because it gives the best correlation with reference data.

Around fifty reference sites are used. Indeed, the range of scenes needs to cover a variety of geographic sites all over the world with a good distribution in latitude to ensure the non-dependency of weather conditions and the visibility of a potential dependency on latitude, date or other criteria.

The performances are given below in terms of median circular error, mean circular error probable at 95%, mean ACT and ALT errors.

4.2.4.1 Unrefined products

Absolute geolocation estimations for S2A and S2B unrefined products exhibits variability during the analysed period of January 2022 to the end of September 2023. Performances on unrefined products are not significant because statistics are calculated on few products.

For S2A, the mean circular error probable at 95% is 13.66 m, while the mean ACT and ALT error is 9.27 m and 5.17 m, respectively. Similarly, for S2B, the mean circular error probable at 95% is 14.74 m, while the mean ACT and ALT error are 7.72 m and 8.58 m, respectively.

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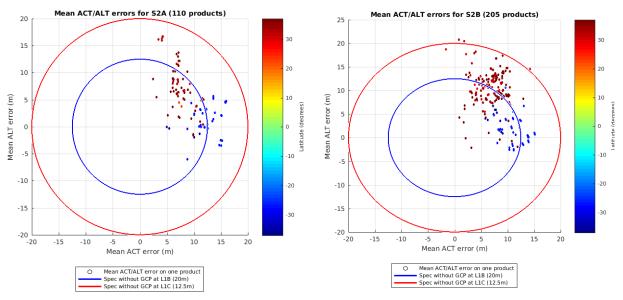


Figure 8: Absolute geolocation performance for unrefined products. Left: S2A, Right: S2B (01.2022 – 09.2023)

4.2.4.2 Refined products

Absolute geolocation performances are compliant to requirements for refined products.

Absolute geolocation estimations for both S2A and S2B refined products show a stable performance over the analysed period from January 2022 to the end of October 2023, with a mean circular error at 95% equal to 8.93 m for S2A and 8.32 m for S2B. For S2A, the mean ACT error is equal to 3.71 m and the mean ALT error is equal to 0.36 m while for S2B the mean ACT error is equal to 3.53 m and the mean ALT error is equal to 1.21 m.

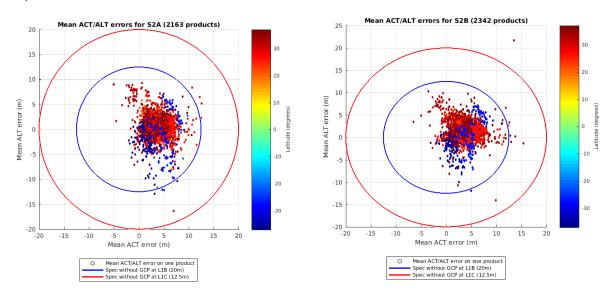


Figure 9: Absolute geolocation performance for refined products. Left: S2A, Right: S2B (01.2022 – 10.2023)

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4.2.5 Multi-Spectral Registration

The multi-spectral evaluation is performed over refined and unrefined Level-1C products acquired over suitable validation sites (flat terrain with good appropriate texture and spectral characteristics). A site in Kazakhstan near Kyzylorda (tile 41TNK) meets the criteria and provides the opportunity to monitor the multi-spectral registration throughout the year (Figure 10). The co-registration requirement (< 0.3 pixel at 99.7% confidence) for both S2A and S2B are within or close to specifications for almost all measured band couples. The 10 m band couples B02/B04 and B02/B08 are slightly above specifications due to large dispersions, but no significant bias is observed. The band couples B05/B11 and B05/B12 are more critical because the spectral bands are on different focal planes (VNIR and SWIR). For S2B, a recalibration of the alignment has been performed in May 2023. For both satellites, a small residual alignment of less than 0.1 pixel in the along-track direction can be observed but is not considered critical.





Figure 10: Location and illustration of the Kyzylorda site (Tile 41TNK) used to perform the inter-band co-registration measurements

Table 4-2: Multi-Spectral co-registration performance (per band couple and detector number) for S2A on 20/10/2023 (top) and S2B on 01/11/2023 (bottom).

Sentinel-2A

	B01	B03	B04	B06	B07	B08	B8A	B09	B11	B12
B02		0.22	0.32			0.48				
B05				0.13	0.17		0.25		0.42	0.49
B02,B08	0.24							0.29		

Sentinel-2B

	B01	B03	B04	B06	B07	B08	B8A	B09	B11	B12
B02		0.18	0.30			0.46				
B05				0.11	0.16		0.25		0.41	0.46
B02,B08	0.13							0.14		

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4.2.6 Multi-Temporal Registration

4.2.6.1 Methodology

The multi-temporal registration error for one tile is estimated as the mean measured error for all control points of the tile. Then the global performance is taken as the 95.5% percentile of the mean shift for all tiles. The performance is measured on the reference band (B04).

4.2.6.2 Refined products

Figure 11 below shows the histograms of the co-registration for pairs of S2A and S2B products. The performance is above the specifications for S2A with a mean circular error of 6.2 m at 95%. For S2B the mean circular error is within the requirements: 4.6 m at 95.45%.

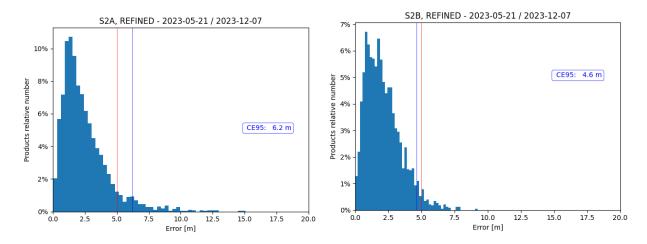


Figure 11: Multi-temporal 2D co-registration errors for refined S2A (left) and S2B pairs (right)

4.2.6.3 All products

The following figure provides the multi-temporal performance for all products, whether refined or unrefined. The performance drops to 8.1 m.

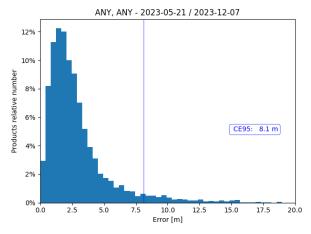


Figure 12: Histogram of the multi-temporal performance for all products (refined and unrefined).

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4.3 Radiometric Performance

4.3.1 Radiometric Uncertainty

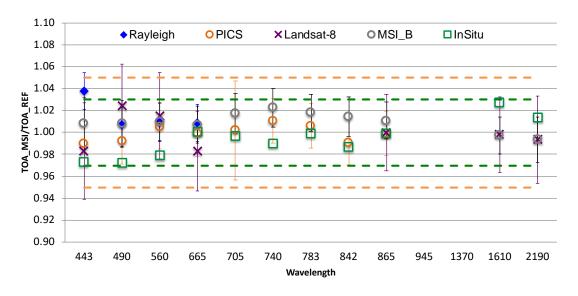
Radiometric validation is performed using several methods:

- * "Rayleigh" method: measurement of the Rayleigh atmospheric backscattering over deep ocean sites.
- Comparison with in-situ data.
- Measurement over well characterized, temporally stable desert areas (Pseudo-Invariant Calibration Sites or PICS).
- Comparison with other sensors such as Landsat-8 OLI (Collection-1 over Libya-4) and cross-comparison S2A vs S2B.
- The DCC method for relative radiometric assessments. Because DCC are high-altitude targets, they are less dependent on an estimation of the radiative transfer through the atmosphere.

The radiometric validation results based on different methods are presented in the figures below. Results are provided for S2A and S2B and for all bands except B09 & B10.

On 25th January 2022, a radiometric harmonization factor between Sentinel-2A and Sentinel-2B (keeping Sentinel-2A as reference) was introduced in operation. Figure 13 and Figure 14 here below shows the radiometric accuracy before the introduction in operation of this radiometric harmonization factor (January 2022) (top figures) and after the introduction in operation on the radiometric harmonization factor (bottom figures).

All results are within the 5% (3%) radiometric accuracy requirement (Goal) respectively.



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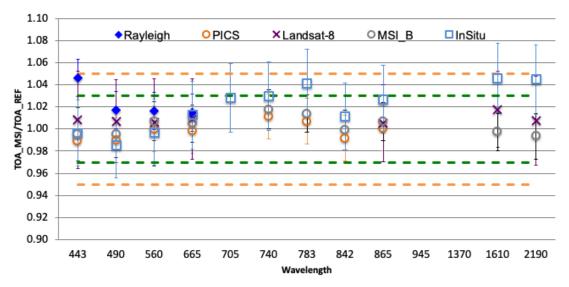
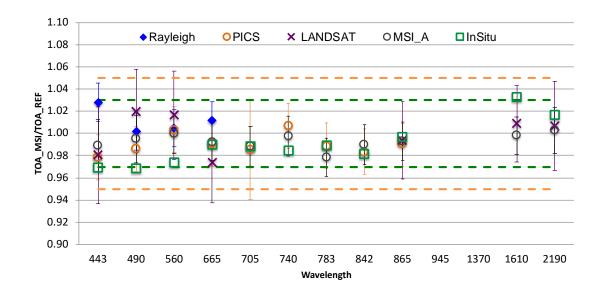


Figure 13: Comparison of radiometric accuracy for all spectral bands (except B09 and B10): ratio of S2A measurement on reference (top) pre-radiometric harmonization between Sentinel-2A and Sentinel-2B in January 2022, (bottom) post-radiometric harmonization up to 10/2023.

Error bars indicate the method uncertainty.



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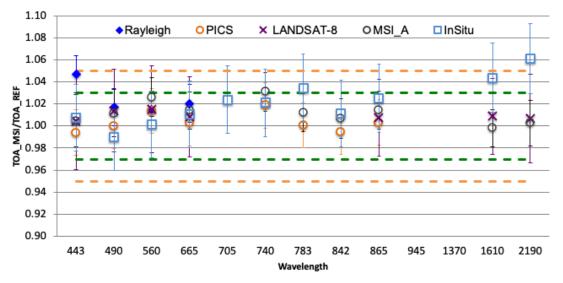


Figure 14: Comparison of radiometric accuracy for all spectral bands (except B09 & B10): ratio of S2B measurement on reference (top) pre-radiometric harmonization between Sentinel-2A and Sentinel-2B in January 2022, (bottom) post-radiometric harmonization up to 10/2023.

Error bars indicate the method uncertainty.

Table 4-3 presents the best estimate of the ratio (gain coefficient) and standard deviations retrieved over the period January 2022 up to October 2023 over the six CEOS-PICS and six Ocean sites. We observe that the gains are within ±3% over all the VNIR bands (B05 excluded due to gas absorption), and compliant with the mission requirements of 5%. The standard deviation of the gain coefficients is found to be of <3%, which illustrates the consistency intra-sites in term of TOA-reflectance.

Table 4-3: Best estimate of S2A and S2B calibration gains coefficient and the standard deviation over the six CEOS-PICS and 6 Ocean sites over the January 2022 - October 2023

Sensor		SZ	2A	S2B			
	Wavelength (nm)	Gain Coefficient	Standard Deviation	Gain Coefficient	Standard Deviation		
B01	443	0.994	0.025	0.999	0.024		
B02	490	0.992	0.018	1.001	0.020		
B03	560	1.001	0.019	1.014	0.023		
B04	665	1.000	0.018	1.004	0.026		
B05	705	N/A	N/A	N/A	N/A		
B06	740	1.011	0.012	1.019	0.011		
B07	783	1.007	0.010	1.000	0.009		
B08	842	0.992	0.014	0.995	0.013		
B8A	865	1.000	0.010	1.003	0.010		

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Time series of measurements are also produced to monitor the evolution in time of the radiometric response, in particular to detect a possible degradation of the diffuser. The current assessment is compatible with the specified stability requirement for all visible and NIR bands (< 1% per year).

The validation of the inter-satellite relative radiometric uncertainty is performed using Deep Convective Cloud (DCC) images. The method is based on statistics of DCC reflectances: a reflectance indicator is computed from DCC pixels reflectances for each band and detector. The reflectances are corrected from atmospheric transmissions between top-of-DCC and top-of-atmosphere using a transmission spectrum obtained from radiative transfer simulations. Previously limited to the VNIR range, the transmission spectrum has been extended to the SWIR and commissioned early October 2022.

The results for the month of September are within the 1% range and stable compared to the last analysed months.

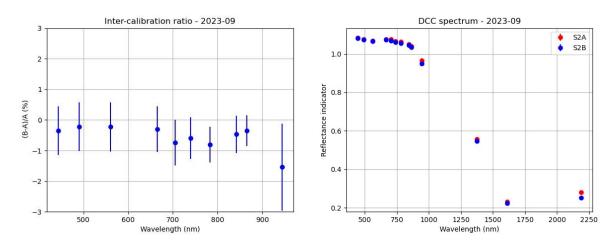


Figure 15: Inter-calibration ratio between S2A and S2B as a function of the wavelength (left) assessed based on acquisitions from September 2023. Reflectance indicator for all wavebands in the VNIR shows an alignment of S2A compared to S2B following the introduction of the radiometric harmonization factor on 01/2022.

4.3.2 Noise

4.3.2.1 Signal-to-Noise Ratio

The SNR is computed based on:

- diffuser acquisitions for short-term performance monitoring,
- homogeneous ground images for long-term performance assessment.

The SNR for both S2A and S2B is exceeding requirements (worst-case >155 for band B8A). The table below provides the mean estimates over 2022.

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Table 4-4: Estimated SNR performance for S2A and S2B at reference radiance based on diffuser acquisitions. Average value over the year 2022 of the mean SNR@Lref per month (mean value over all the valid pixels for the monthly sun diffuser acquisition) and maximum difference over the months.

Spectral Band	B1	B2	В3	B4	B5	В6	В7	B8	B8A	В9	B10	B11	B12
Ref. radiance [W/m²/sr/μm]	129	128	128	108	74.5	68	67	103	52.5	9	6	4	1.5
S2A Mean SNR@Lref	1367	206	235	218	243	212	220	213	155	215	383	156	165
Max deviation	0,7%	0,3%	0,2%	0,2%	0,2%	0,3%	0,4%	0,4%	0,2%	0,6%	0,8%	0,7%	0,5%
S2B Mean SNR@Lref	1330	208	236	224	242	217	226	224	165	231	394	164	169
Max deviation	1,4%	0,6%	0,6%	0,5%	0,6%	0,6%	0,7%	0,7%	0,6%	1,3%	1,1%	1,2%	0,9%
Requirement	129	154	168	142	117	89	105	174	72	114	50	100	100

As seen in the figure below, the noise characteristics are very stable over time.

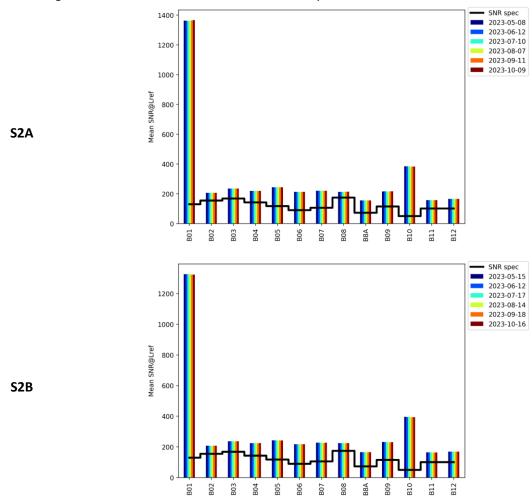


Figure 16: Evolution of the SNR performances based on diffuser acquisitions for S2A from 08/05/2023 to 09/10/2023 (top) and S2B from 15/05/2023 to 16/10/2023 (bottom)

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The SNR is also computed over cloudless homogeneous landscapes. For this purpose, a number of pseudo-invariant calibration sites (PICS) are used, including sites in Libya, Mali, Saudi Arabia and Mauritania. Small homogeneous regions are identified from these landscapes and the SNR is estimated from a Fourier Transformation of these regions. The results are consistent with the ones issued from the diffuser. The calculated SNRs in both sensors are stable over time in every band and consistently exceed the requirements.

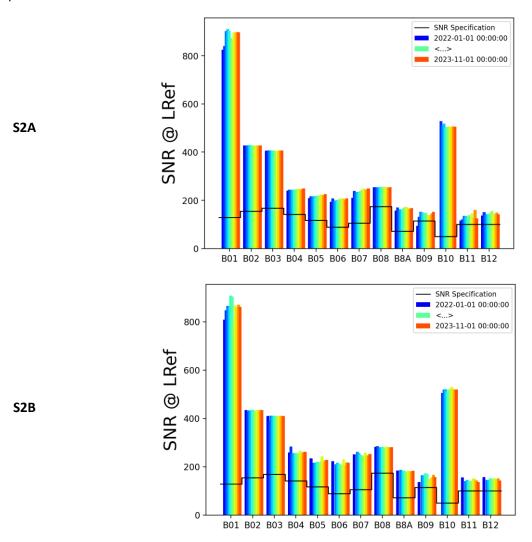


Figure 17: Evolution of the SNR performances based on homogeneous natural acquisitions for S2A (top) and S2B (bottom) from 01/01/2022 to 01/11/2023

4.3.2.2 Fixed Pattern Noise

Another aspect of the image noise is the so-called Fixed Pattern Noise (FPN): this is the residual pixel radiometric error after equalization. The performance computed on sun diffuser acquisitions is estimated with operational equalization coefficients resulting from the sun calibration of the previous month. Therefore, it is an estimate for the highest changes of the sensor response till the previous calibration. However, the FPN is better than the specification for all bands except for a few pixels on bands B10 and B11. The monthly update of the calibration coefficients resolves the few pixels with an equalization fault.

Figure 18 shows typical estimates of the FPN, for the different spectral bands.



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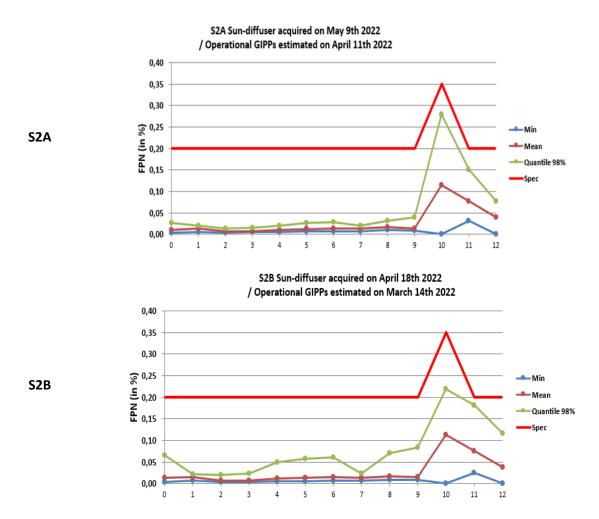


Figure 18: Fixed Pattern Noise (residual error after equalization) measured on diffuser images for S2A (top) and S2B (bottom). Blue curve: min FPN, marron: mean, green: 98 percentile, red: specified value.

The FPN is also computed on images over radiometrically uniform natural targets like deserts or snow. A selection based on the cloud cover is performed.

As for the assessment performed over diffuser acquisitions, the performance computed is better than the specification for all bands. For the band B10 the method is not applicable as the ground is not visible. Figure 19 shows the average values obtained using products acquired in August 2023 for the different spectral bands.

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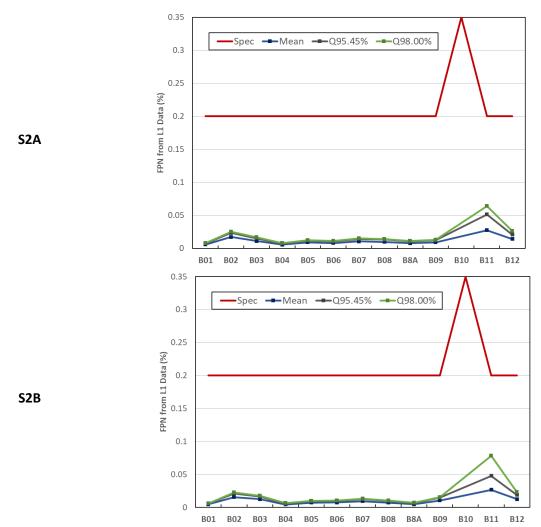


Figure 19 : Fixed Pattern Noise (residual error after equalization) measured on homogeneous natural images for S2A (left) and S2B (right) for Septembre 2023.

Blue curve: mean FPN, grey curve: Q95.45%, green curve: Q98.00% and red curve: specified value.

4.3.3 Modulation Transfer Function

The Modulation Transfer Function (MTF) has been estimated by analysing images with sharp edges or lines for all bands (except B10 for which in-orbit assessment is difficult and for B1 and B9 in ACT: no suitable areas have been found).

Globally, the values measured in flight are consistent with In Orbit Tests (IOT) measurements and are stable in time except for 2021. Indeed, the 2021 measurements appear to be biased compared to the other measurements. No evolution in the MTF assessment is observed when the 2021 measurements are not considered.

The MTF requirements are satisfied for all bands (minimum specified to 0.15 for all bands). The MTF is above the maximum value requirement for B5, B6, B7 and B8A for the across and along track directions. Note that only the minimum value requirement has a direct impact on image quality; this requirement is satisfied for all bands.

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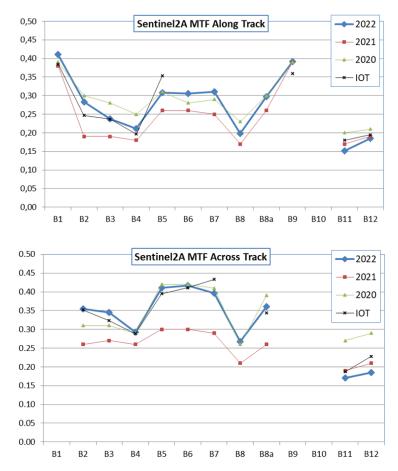
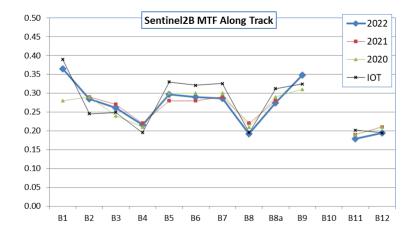


Figure 20: MTF performance assessments for S2A (along and across track) performed using products from last 3 years and compared to IOT measurements.



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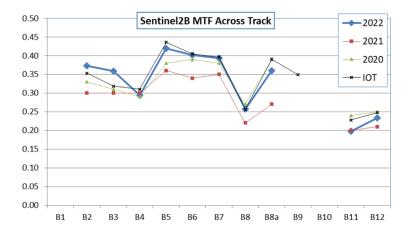


Figure 21 : MTF performance assessments for S2B (along and across track) performed using products from last 3 years and compared to IOT measurements.

The following table gives the measured values.

Table 4-5: S2A and S2B performances assessments using products from 2022.

2022 MTF	B1	B2	В3	B4	B5	В6	B7	B8	B8a	В9	B10	B11	B12
S2A ALT	0.41	0.28	0.24	0.21	0.31	0.31	0.31	0.20	0.30	0.39		0.15	0.19
S2A ACT		0.35	0.35	0.29	0.41	0.42	0.40	0.27	0.36			0.17	0.18
S2B ALT	0.36	0.28	0.26	0.22	0.30	0.29	0.29	0.19	0.27	0.35		0.18	0.19
S2B ACT		0.37	0.36	0.29	0.42	0.40	0.39	0.26	0.36			0.20	0.23

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5 Pixels Status

5.1 Defective pixels

In the following tables are listed the identified defective pixels **since the beginning of year 2023**. The radiometry of these pixels is then replaced by an interpolation of neighboring pixels.

Table 5-1: Defective pixels on S2A

Band	Detector	Pixel number (from 0)	Last update	Observations
B11	11	24	24/04/2023	Pixel in the inter-detector area. Not used for the resampling from L1B to L1C products. The update of the R2DEPI configuration file aims to be consistent for L1B images only. This pixel has been considered defective for radiometric calibrations since 2019.

Table 5-2: Defective pixels on S2B

Band	Detector	Pixel number (from 0)	Last update	Observations
B12	4	1121	11/04/2023	-

Please refer to the <u>Sentinel 2 Annual Performance Report</u> covering the year 2022 to retrieve the list of older defective pixels for both S2A and S2B.

5.2 Dust deposit

Following the Sentinel-2B radiometric calibration from the Sun acquisition on October 16th, an unusual increase of the equalization coefficients by about 1.1%, for pixels number 459 to 491, of the band B05, detector 7 was observed.

A wide strip is clearly noticeable (see Figure 22) on a desert image acquired on October 16th at 06:31 UTC. Previous experience has enabled to link this phenomenon to a dust deposit on the detector. The updated equalisation coefficients correct this phenomenon.



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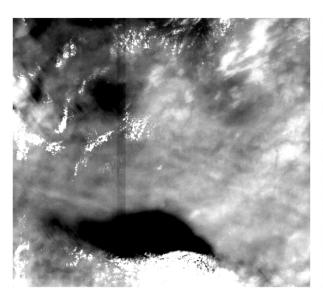
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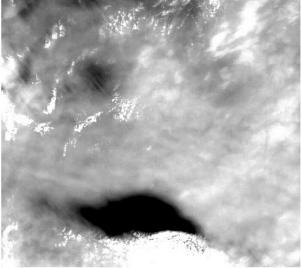


Figure 22: Sentinel-2B Level-1B acquisition on 2023-10-16 at T06:31:37 for detector D07 and band B05. On the left, the image is equalized with the R2EQOG calibration files from September while on the right side, the image is equalized with the updated R2EQOG calibration files from October.

The update of the R2EQOG calibration files has been active in operation since 2023-10-20T00:30:00, from the orbit 34577. Analysis of older images highlighted that the wide strip on B05 D07 might be visible on products acquired between October 8th and October 20th 2023 at 00:30 UTC.

5.3 Reset Spike pixels

During the MSI design phase, it has been identified that a few pixels of the 10 m bands are affected by an electronic crosstalk during detector read-out. This results in errors which can reach a few digital counts, depending on the observed scene.

The list of affected pixels can be retrieved in the <u>Sentinel 2 Annual Performance Report</u> covering the year 2022.



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6 Product Features

Some known product features are visible on Sentinel 2 products.

These features are generated by:

- the spectral response non-uniformity,
- parallax effects created by the staggered configuration of the focal plane,
- surface reflectance effects,
- misregistration of High-Altitude Objects,
- gradient crosstalk on band B12,
- data-strip overlap.

Please refer to https://omcs.atlassian.net/wiki/spaces/CSWK/pages/407406098/S2+Products#L1C-product-Features for more details and examples of the known Sentinel 2 product features, as well as to the https://omcs.atlassian.net/wiki/spaces/CSWK/pages/407406098/S2+Products#L1C-product-Features for more details and examples of the known Sentinel 2 product features, as well as to the https://omcs.atlassian.net/wiki/spaces/CSWK/pages/407406098/S2+Products#L1C-product-Features for more details and examples of the known Sentinel 2 product features, as well as to the https://omcs.atlassian.net/wiki/spaces/cswk/pages/407406098/S2+Products#L1C-product-Features

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7 Product anomalies

This section describes the L1C product anomalies that occurred in 2023. Please refer to the <u>Sentinel 2 Annual Performance Report</u> covering the year 2022 or to the on-line Sentinel-2 anomaly database https://s2anomalies.acri.fr/anomalies to have the full list of anomalies.

Each anomaly is tagged with a code "#N" allowing linking it to a given processing baseline through the three tables provided in the sub-sections below.

7.1 Level-1C processing anomalies

7.1.1 Introduction

The table below summarizes the known processing anomalies affecting the current L1C production.

	Baseline number	05.09
Anom. ID	06/12/2022	
	Anomaly title	
73	Inconsistent data loss report	Some products
83	QUALIT_MSK not detecting all missing packets	A few products
86	Footprint anomaly at antemeridian	Some products

Table 7-1: L1C processing anomalies

7.1.2 Inconsistent data loss report (#73)

This anomaly concerns products affected with missing packets (data loss). The reports in the Datastrip Metadata and the Granule metadata are inconsistent. Known occurrences are listed below:

- \$ S2A_MSIL1C_20220110T155631_N0301_R054_T18UXE_20220110T175004.SAFE has missing packets on bands 1,7,8A,9, and 12 but reports 0 lost packet at datastrip level
- \$ S2B_MSIL1C_20211215T234509_N0301_R044_T54DVM_20211216T003204.SAFE has missing packets on band 3 but reports 0 lost packet at datastrip level
- \$ S2B_MSIL2A_20220131T161509_N0400_R140_T17RLN_20220131T185140.SAFE has missing packets reported in the datastrip metadata but missing from the tile metadata.

7.1.3 QUALIT_MSK not detecting all missing packets (#83)

All the lost packets are not flagged in the quality masks of some products. The cause of this problem has been found by the processing chain maintainers, and a fix will be implemented.

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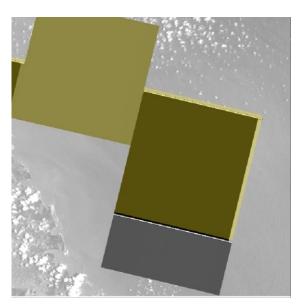


Figure 23: B02 of S2B_MSIL1C_20230110T073159_N0509_R049_T36KYC_20230110T092744 in background with band 3 (dedicated to lost packets) of the corresponding MSK_QUALIT superimposed in yellow. All the black pixels, due to data loss, in B02 are not flagged in the quality mask.

7.1.4 Footprint anomaly at antemeridian

The footprint of S2A and S2B products generated from datastrips crossing the antemeridian and acquired between 19/10/2023 and 31/10/2023 is not displayed correctly on <u>Copernicus Data Space Ecosystem</u> (CDSE). The issue has been solved and the impacted products are now displayed correctly.

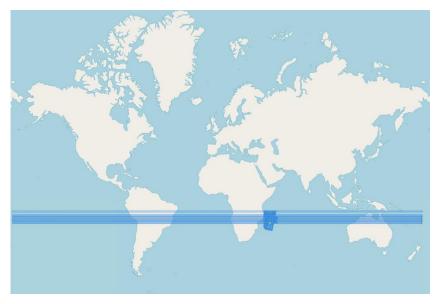


Figure 24: Footprint of S2 tiles crossing the antemeridian were not displayed correctly

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7.2 Instrument anomalies

7.2.1 Introduction

The table below provides the status of anomalies which are not related to processing and can therefore not be corrected through reprocessing. It complements the table provided in the sub-section above.

Table 7-2: On-board Anomalies.

Anomaly ID	Anomaly title	Criticality	Unit	Affected products	Product status
77	Geolocation error after collision avoidance manoeuvre	Minor	S2A	Orbit 39313	Available
85	Geolocation error after collision avoidance manoeuvre	Major	S2A	Orbit 42831	Available (to be removed)
87	Geolocation error after collision avoidance manoeuvre	Major	S2A	One datatake from orbit 43812	Available (to be removed)
88	Missing LO granules causing bad processing	Major	S2B	One datastrip from orbit 34954	Available (to be removed)

7.2.2 Geolocation error after collision avoidance manoeuvre (#77)

Some products acquired shortly after a collision avoidance manoeuvre (S2A orbit 39313 on 01/01/2023) are affected with a geolocation error of about 35 m. As the products are mainly cloudy and over the ocean, they have been kept into the archive.

7.2.3 Geolocation error after collision avoidance manoeuvre (#85)

Products from datastrips DS_2APS_20230904T082658_S20230904T062632, DS_2APS_20230904T083522_S20230904T063121 and DS_2APS_20230904T090309_S20230904T063906, acquired shortly after a collision avoidance manoeuvre on 04/09/2023 are impacted by a geolocation error higher than 30 m. These products will be removed from the archive.

7.2.4 Geolocation error after collision avoidance manoeuvre (#87)

Following a collision avoidance manoeuvre on 2023-11-11, one datatake (GS2A_2023111T210921_043812_N05.09) suffers from a high geolocation error. Corresponding products should be removed from the archive.

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7.2.5 Missing LO granules causing bad processing (#88)

Because of snow on radome at Svalbard station, several LO granules were lost, causing an issue in the processing of one datastrip. The impacted products will be removed from the archive.

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8 General information on products

8.1 Insights into the Copernicus Collection-1

The Collection-1 reprocessing will provide consistent Sentinel 2A and Sentinel 2B time series with a uniform processing baseline (PB 05.00) and optimized calibration.

The L2A surface reflectance product will be compliant with the CEOS Analysis Ready Data for Land (CARD4L) standard from 2015 to the present.

The improvements introduced in recent baselines will be generalized to the whole time series:

- Geometric refining using the high-quality Copernicus Digital Elevation Model (introduced in PB 03.00),
- Harmonized radiometry after alignment of S2B on S2A (introduced with PB 04.00),
- Most recent product format for L1C and L2A with radiometric offset, quality masks in raster format, L2A quality indicators, DOI (introduced in PB 04.00),
- Improved L2A processing algorithms for scene classification and surface reflectance (aligned with PB 04.00).

In addition, the PB 05.00 will provide some specific improvements over the current 04.00 baseline:

- Optimization of the applicability of successive radiometric and geometric calibrations,
- Reliable quality mask for radiometric saturation,
- Identification of defective pixels from missing instrument source packets in L2A Scene Classification layer,
- Use of the Copernicus Digital Elevation Model at 30 m resolution.

Collection-1 products are distributed on CDSE (Collection-1 flag) and on three other platforms:

- https://creodias.eu.: the data catalogue is accessible at https://explore.creodias.eu/. To query only Collection-1 products (PB 05.00), you can write "_N0500_" in the research bar of the catalogue, after selecting "Partial product name match".
- https://www.onda-dias.eu: the data catalogue is accessible at https://catalogue.onda-dias.eu/catalogue/. To query only Collection-1 products (PB 05.00), you can write "*_N0500_*" in the research bar of the catalogue.
- https://mundiwebservices.com: L1C Collection-1 products can be found at https://mundiwebservices.com/geodata/S2R_MSI_L1C, and L2A Collection-1 products at https://mundiwebservices.com/geodata/S2R_MSI_L2A.

Collection-1 production has started with December 2021 products and goes in reverse chronological order of sensing time. In November 2023, Collection-1 products from September 2019 to December 2021 are available. Please note that the period reported is considered available for the most part, while gradually densifying in particular on the side of the earlier months of the period.

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Additional information regarding the status and accessibility of Collection 1 reprocessed data can be found on: https://sentinels.copernicus.eu/web/sentinel/technical-guides/sentinel-2-msi/copernicus-sentinel-2-collection-1-availability-status.

8.2 Product Format

On December 6th 2016, a new naming convention has been introduced (Product Specification Document version 14). The new convention leads to shorter product paths with less redundancy of information. The product name now includes the acquisition date and a "product discriminator" which is related to the acquisition date but can be different in some instances.

A reformatting of the Data Hub product archive to the single-tile, short name format is currently in progress. The JP2000 images are not affected by the reformatting.

Note that the product footprint for all products generated before July 20th 2016 include areas of No Data, while for the later product the footprint outlines valid pixels only.

8.3 Off-line products

Sentinel-2 products are kept online in the Copernicus data hubs according to a sliding window period of at least one month. At the end of the retention period, products are removed from the online storage, and they will be retrieved on demand from the Long-Term Archive (LTA). Products retrieved from the LTA will be different from the original ones delivered in Near Real Time production:

- The product discriminator (the second date in the product) will be different. However, the zip file provided with the delivery will keep the name of the original product.
- The product will be restored using the latest applicable format (currently compact, single tile format, PSD v14.9).
- The GENERATION_TIME field in the User Product metadata will also reflect the date of the retrieval from the LTA.

See https://scihub.copernicus.eu/userguide/DataRestoration for more details.

8.4 Reprocessed products

Two situations can lead to a recovery reprocessing and update of the CDSE archive:

- Products affected by major anomalies tracked in the Sentinel-2 anomaly database,
- Datastrips with missing L1C tiles. In this case the products are not tracked in the anomaly database.

In both cases, the original products are removed and replaced by products with a more recent generation time. However, in the latter case, the original products can still be considered as valid.